

DIVERSITA+

Extends the ML on Edge Technology to the Underwater World

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Preface

ABOUT DIVERSITA+

The essence of the Project Diversita was using Machine Learning on Edge technology to recognize specific patterns and react to different results accordingly.

While Diversita was built for land animals, here I propose the Diversita+—an extension of scenarios for the technology framework—for underwater use.

The dataset to train the model could be optical camera images for individual species like shark, ray, barracuda. It could also be sonar reflection pattern.

In general, Diversita+ could be used to assist beach safety monitoring, marine fauna research, and water purity monitoring.

MENU



Huntaway 3







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PROBLEM IDENTIFICATION

Shark/stingray/barracuda may come to the beach to attack swimmers/surfers.

It is tough for lifeguards to monitor an entire beach, especially when there is a strong sunshine reflection from the sea or high waves beating the beach.

Once the attack happens, the consequence might be lethal.

USER PERSONA



Olivia

Gender: female

Age: 31

Occupation: lifeguard at Australia Lifeguard Service

Location: Gold Coast, Queensland, Australia

Work routine: monitors a two km. long beach from 10 am to 5 pm, mainly watches for drowning or shark attack.

Pain point: the beach is crowded, very hard to identify anomaly; in the morning, the reflection of sunshine on the sea surface makes it even harder to monitor.

Quote: "It's tough to keep vigilance all day long. I know once the shark attack happens, the consequence would be severe."



CONCEPT DESCRIPTION

Huntaway is a fencing system deployed at beaches or similar places to monitor and fend off marine species that threaten human life.

A node device of the system can detect aquatic life species by capturing images of nearby animals with its optical cameras and sonar array. The pictures and movement vector pattern will be processed with a pretrained on-edge neural network to verify if there are target species.

If the captured data triggers the alert rule, the nearby lifeguard will be notified the species identified and its location.

The electrode array could deter shark by emitting electric current to interfere the ampullae of Lorenzini in their noses.



WORKFLOW & DESIGN REQUIREMENT

1. DETECT

use ultrasonic array to generate reflection image;

use optical camera to generate visual image

- buoyancy provider/intallation basement
- sonar array
- camera array

2. ANALYZE	3. NOTIFY	4. INTERVENE				
use ML model to recognize threatening species based on imaging results/moving vector pattern	notify lifeguard of coming threatening species with wireless connectivity	use electric field pulse to expel sharks				
COMPONENTS						
 power source: solar panel/ battery computation module cooling 	• antenna	• deterrent module				



SKETCHES



front view

top view

Note: the cooling fin was cancelled during the CAD.

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perspective view



CONCEPTUAL CAD



top/side view with dimensions (mm)

computer graphics rendering





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PROBLEM IDENTIFICATION

Researchers spend long hours to manage video trailers and photos for marine life research—most part of the trailer are worthless, and researchers need to pick out sections that capture frames of interests.

USER PERSONA



Grace Gender: female

Age: 29

Occupation: marine life researcher

Location: San Diego, CA

Work routine: dives at research sites, take photos of marine life underwater and marks the spot; spends long hours organizing research data.

Pain point: most of the research time was spent on collecting and organizing data.

Quote: "Although it's 2018, we are still working in a Middle Ages way. What if I want to study the transpacific marine life distribution, will our team soak in the salt water forever?"



CONCEPT DESCRIPTION

Comparing with the voyage range of a ship, most marine life individuals have a relatively small living circle.

Inspired by remora, a small fish that attach itself to a passing shark/whale, usually on the belly or underside, to take advantage of the large host's protection and food residual during its long-range travel. I propose the Remora concept—an ML on Edge device that is installed at the side of a ship below the ship's waterline, it combines images from an optical camera and a sonar array, recognizes the marine life species and geo-tag the location where the data was collected.

By attaching a species recognition and geo-tagging enabled underwater device to the bottom of a research ship, researchers can collect data on marine fauna distribution ocean-wide. Just like a floating satellite.



WORKFLOW & DESIGN REQUIREMENT

1. SCAN

use ultrasonic array to generate reflection in

use optical camera to generate visual image

- attaching module: magnet, mounting poin mechanic jack
- sonar array
- camera
- lighting
- antenna

	2. ANALYZE	3. SYNTHESIZE
mage;	use ML model to recognize species based on imaging results/moving vector pattern	integrate recognition result with geo information, produce a visualized report on the findings
	COMPONENTS	
nt for	computation module	 data processing software



SKETCHES





front view

side view

Note: the hydro turbine power generator concept was abandoned.

perspective view





side/front view with dimensions (mm)

diversita

computer graphics rendering





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PROBLEM IDENTIFICATION

Phytoplankton are important parts of the marine biological energy and carbon circulation system.

By now, researchers need to travel to research spots to sample tubes of liquid material periodically. The time spent en route and lodging at the research site costs research fund but have no direct contribution to research itself.

USER PERSONA



Valier

Gender: male

Age: 34

Occupation: plankton scientist at NOAA

Location: Seattle, WA

Work routine: samples water in the Elliot Bay every two weeks, uses a microscope to identify plankton species and counts their quantity.

Pain point: traveling to the research spot takes considerable time and consumes the research fund.

Quote: "What we need is just the data of the sample. Last year we went to the Aleutian Islands just for some water samples, but it cost us \$700K—most were paid for the research ship."



CONCEPT DESCRIPTION

Seahorse is a device that integrates an electronic microscope with an edge computing module.

It can sample plankton periodically as programed. Images captured will be processed by local computing power. ML models for plankton recognition will interpret the images and generate a research log recording the species, density, and time of capturing.

The result can either be collected via wireless Internet or storage media.

WORKFLOW & DESIGN REQUIREMENT

1. TAKE IN 2. LOCK The device takes in 10 After taking in the mL of sample at one sample liquid, the sample chamber wil time. locked. • sample intake • chamber lock



	3. CONDENSE	4. SCAN	5. RELEASE	6. ANALY	
ll be	The device will filter excessive water from the sample with a semipermeable membrane, to get the sample ready for microscope scan.	A microscope inside the device will scan the sample under constant flash lighting.	When the scan completes, the device evacuates the sample chamber, archives the used semipermeable membrane and washes the sample chamber for next sampling.	The device analyze scanned image wi ML model trained plankton dataset, generates a sampl record.	
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COMPONENTS					
	• compression mechanics	 flash light internal microscope scanner 	• exhaust	computation meantenna	



SKETCHES





top view

side view

CONCEPTUAL CAD



top/side view with dimensions

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computer graphics rendering



Appendix

REFERENCE

- Huveneers, C., Rogers, P. J., Semmens, J. M., Beckmann, C., Kock, A. A., Page, B., & Goldsworthy, S. D. (2013). Effects of an electric field on white sharks: in situ testing of an electric deterrent. PloS one, 8(5), e62730. doi:10.1371/journal. pone.0062730
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RISKS AND PROBLEMS TO BE SOLVED

Huntaway

- The consequence of a false negative might put someone's life into danger.
- How to clean the lens?

Remora

- The surface of a ship's underwater part may have biological attachments, which will make the mounting not reliable.
- If the speed of the ship is high, vacuum bubbles may interfere with sonar/optical camera.

Seahorse

- How to retrieve the device back?
- How to keep the device relatively stationary in the deep ocean (thousands of meters deep) where there is nothing to attach the device?

